TIENet[®] 360 LaserFlow[®] Ex Velocity Sensor

Installation and Operation Guide





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Foreword - Water and Wastewater Products

This instruction manual is designed to help you gain a thorough understanding of the operation of the equipment. Teledyne ISCO recommends that you read this manual completely before placing the equipment in service.

Although Teledyne ISCO designs reliability into all equipment, there is always the possibility of a malfunction. This manual may help in diagnosing and repairing the malfunction.

If a problem persists, call or e-mail Teledyne ISCO technical support for assistance. Simple difficulties can often be diagnosed over the phone. For faster service, please have your serial number ready.

If it is necessary to return the equipment to the factory for service, please follow the shipping instructions provided by technical support, including the use of the Return Merchandise Authorization (RMA) specified. Be sure to include a note describing the malfunction. This will aid in the prompt repair and return of the equipment. No item may be returned for service without a Return Merchandise Authorization (RMA) number issued by Teledyne.

Teledyne ISCO welcomes suggestions that would improve the information presented in this manual or enhance the operation of the equipment itself.

Teledyne ISCO is continually improving its products and reserves the right to change product specifications, replacement parts, schematics, and instructions without notice.

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Warranty and Operation Manuals can be found on our website:

www.teledyneisco.com

EAR-Controlled Technology Subject to Restrictions Contained on the Cover Page

General Warnings

Caution: Use of controls or adjustments or performance of procedures other than those specified herein may result in hazardous radiation exposure.

Wavelength: 655 nm

Maximum Power: 5 mW

Before installing, operating, or maintaining this equipment, it is imperative that all hazards and preventive measures are fully understood. While specific hazards may vary according to location and application, heed the following general warnings:



Avoid hazardous practices! If you use this instrument in any way not specified in this manual, the protection provided by the instrument may be impaired.

The LaserFlow Ex MUST be installed in accordance with control drawing, in Figure 2-1 thru Figure 2-3 in this manual, and in accordance with the requirements of the authority that has jurisdiction for the installation of equipment in hazardous areas at your specific installation site.

The certified control drawing details the only approved method of installing the LaserFlow Ex. Where specific ISCO part numbers appear, they represent the only approved equipment certified to be used with the LaserFlow Ex. Any equipment substitutions or installations not specifically detailed on the control drawing will automatically void the intrinsically safe certification of the LaserFlow Ex and could result in fire or explosion!

Hazard Severity Levels	This manual applies Hazard Severity Levels to the safety alerts,
	These three levels are described in the sample alerts below.

Cautions identify a potential hazard, which if not avoided, may result in minor or moderate injury. This category can also warn you of unsafe practices, or conditions that may cause property damage.

Warnings identify a potentially hazardous condition, which if not avoided, could result in death or serious injury.

DANGER – limited to the most extreme situations to identify an imminent hazard, which if not avoided, will result in death or serious injury. Hazard Symbols

The equipment and this manual use symbols used to warn of hazards. The symbols are explained below.

Hazard Symbols			
Warnings and Cautions			
\triangle	The exclamation point within the triangle is a warning sign alerting you of important instructions in the instrument's technical reference manual.		
<u>Á</u>	The lightning flash and arrowhead within the triangle is a warning sign alert- ing you of "dangerous voltage" inside the product.		
Symboles de sécurité			
\triangle	Ce symbole signale l'existence d'instructions importantes relatives au pro- duit dans ce manuel.		
<u>Á</u>	Ce symbole signale la présence d'un danger d'électocution.		
Warnungen und Vorsichtshinweis	e		
\triangle	Das Ausrufezeichen in Dreieck ist ein Warnzeichen, das Sie darauf auf- merksam macht, daß wichtige Anleitungen zu diesem Handbuch gehören.		
<u>Á</u>	Der gepfeilte Blitz im Dreieck ist ein Warnzeichen, das Sei vor "gefährlichen Spannungen" im Inneren des Produkts warnt.		
Advertencias y Precauciones			
\triangle	Esta señal le advierte sobre la importancia de las instrucciones del manual que acompañan a este producto.		
<u>Á</u>	Esta señal alerta sobre la presencia de alto voltaje en el interior del producto.		

TIENet® 360 LaserFlow Ex® Velocity Sensor

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TIENet[®] 360 LaserFlow Ex[®] Velocity Sensor

Section 1 Introduction

1.1 LaserFlow Ex

The TIENet 360 LaserFlow Ex sensor is an Area Velocity flow measurement device that remotely measures flow in open channels with non-contact Laser Doppler Velocity Sensing and non-contact Ultrasonic Level Sensing technologies. The sensor uses advanced technology to measure velocity with a laser beam at single or multiple points below the surface of the water stream.



Figure 1-1 Basic LaserFlow Ex system (showing both AC and battery-powered options)

1.2 Design of LaserFlow Ex	The LaserFlow Ex sensor consists of a housing with two mea- surement technologies working together.
1.2.1 Measurement Technology	The laser velocimeter has a laser diode that serves as both transmitter and receiver of a laser light beam. The Doppler-shifted signal frequency is used to determine flow stream velocity.
	The ultrasonic level transducer determines the stream's level by emitting an ultrasonic pulse and measuring the time it takes for the echo to return from the stream's surface. The transducer is both pulse transmitter and echo receiver.
1.2.2 Cabling	The LaserFlow Ex sensor is available with a 10m or 23m standard length cable. Custom cable lengths are also available up to 108 feet.
	The maximum recommended distance between the TIENet Barrier and the LaserFlow Ex is 33 meters.
1.3 Operation	The laser velocimeter uses a laser beam to generate a source frequency light, which is focused at points below the surface of the flow stream. The light is scattered back to the laser. The returned light is frequency shifted due to the Doppler effect. The lens that focused the laser light below the surface of the flow stream focuses the returned light back into the laser. The source light and shifted light frequencies are separated to determine a Doppler shift, which is then used to calculate flow stream velocity.
	The ultrasonic level transducer emits multiple ultrasonic pulses per second. Between pulses, the transducer switches from transmitter to receiver. When the transducer receives the echo from the water's surface, the sound energy is converted into an electrical signal. The signal is then amplified and processed by the flowmeter into an echo-received signal. The time between the transmitted pulse and the echo-received signal is proportional to the distance between the transducer and the liquid surface, which is then used to calculate level. Because the speed of the pulse through air varies with temperature, compensation is built-in. A temperature sensor inside the level transducer measures ambient temperature. The microprocessor program automatically compensates for speed-of-sound changes caused by air-temperature changes.
	surement point for both level and velocity measurement.

1.4 Technical Specifications

Table 1-1 provides technical specifications for the LaserFlow Ex. $\,$

Table 1-1 LaserFlow Ex Sensor Specifications ^a			
Size (H x W x D)	18.0 x 9.5 x 23.5 in	45.7 x 24.1 x 59.7 c,	
Cable Lengths ^b	10 or 23 m	32.8 or 75.5 ft	
	NOTE: 33 m max from LaserFlo	ow Ex to TIENet barrier.	
Weight	24.8 lbs (11.25 kg)		
Materials	Conductive Carbon Filled ABS Kynar® ^c , Anodized Aluminum, I	Plastic, SST, Conductive UV Rated PVC	
Enclosure (self-certified)	IP68 (Submerged @ 2 m depth	for 72 hrs)	
Certification	CE EN61326; FDA CDRH 21CF	FR1040; IEC 60825-1	
	Class 1, Div 1, Gr. C–D, T4, Ex Class1, Zone 0, Ex/AEx ia op is Ex ia op is IIB T4 Ga IECEx II 1 G Ex ia op is IIB T4 G -10 °C < Tamb < +60 °C	ia IIB T4 Ga Ga	
Laser Class	Class 3R		
Laser Wavelength	655 nm		
Laser Exit Angle	45° ±3°		
Input Voltage (Operating)	10 to 13VDC Recommend; 8VD	C Minimum	
Input Power (Operating)	1.6W/200mA		
Electrical Connections	Signature flowmeter, Screw Ter ule, TIENet Plug, TIENet Barrie	minal, 2160 LaserFlow Mod- r	
Temperature Range	Operating: 14 to 140 Storage: -40 to 140	°F (-10 to 60 °C)) °F (-40 to 60 °C)	
Flow Accuracy	±4% of Reading (Typical under ditions.)	less than half pipe flow con-	
Velocity Measurement			
Technology	Non-Contact, Subsurface Laser (U.S. patent 8,339,584 and pate	Doppler Velocity ents pending)	
Measurement Range	0.5 ft/s to 15 ft/s	0.15 to + 4.6 m/sec	
Number of velocity readings per measurement	1 to 3 (selectable measurement	t points)	
Maximum distance: liquid surface to bottom of sensor	3m (10 ft)		
Minimum depth for velocity measurement	0.01m (0.5 in)		
Minimum Velocity	0.5 ft/s (0.15 m/s)		
Deadband	Zero deadband from bottom of	LaserFlow Ex sensor ^d	
Accuracy in full pipe or lower flow conditions	±0.5% of reading ±0.03 m/s (0.	1 ft/s)	

Table 1-1 LaserFlow Ex Sensor Specifications^a (Continued)

Level Measurement		
Technology	Non-Contact Ultrasonic Signal	
Measurement Range	0 to 3 m (0 to 10 ft) from measurement point	
Accuracy @ 22 °C	$\pm 0.006m$ (0.02 ft) at < 1ft level change; $\pm 0.012m$ (0.04 ft) at > 1ft level change	
Ultrasonic Temperature Coefficient	\pm 0.0002 x D (m) per °C (± 0.00011 x D (ft) per °F) (Where D is the distance from transducer to liquid surface)	
Ultrasonic Beam Angle	10° (5° from center line)	
Ultrasonic Signal	50KHz	
Deadband	Zero deadband from bottom of LaserFlow Ex sensor	

a. All specifications are subject to change without notice.

- b. Custom cable lengths also available.
- c. Kynar® is a registered trademark of Arkema, Inc.

d. Deadband for 310 remote ultrasonic sensor varies due to the type of mounting hardware.

1.5 Accessories	Accessories us below. Refer to	sed in sensor installation are briefly described the next section for ordering information.
1.5.1 Ordering Information	Options and ac ISCO's Custom	ccessories can be purchased by contacting Teledyne her Service Department.
	Teledyn	e ISCO
	Custome	r Service Dept.
	P.O. Box	82531
	Lincoln,	NE 68501 USA
	Phone:	800 228-4373
	FAX:	402 465-3022
	E-mail:	IscoInfo@teledyne.com
Cord grip fitting, ³ /4" NPT, for TIE	Net cable	

Signature flowmeter Exterior desiccator	
(required for use with 330 and 350 TIENet devices)	. 60-4304-092
Silica gel desiccant, 1.5-lb container	. 60-2004-233
Permanent Wall Mounting Hardware Kit	. 60-4364-003
Refer to Section 2.6.1 Wall Mount Installation for additional information.	

Mote

Teledyne ISCO uses FreeRTOS version 5.4.2 in its TIENet devices. In accordance with the FreeRTOS license, FreeRTOS source code is available on request. For more information, visit www.FreeRTOS.org.

1.6 Unpacking Instructions

When the system arrives, inspect the outside packing for any damage. Then carefully inspect the contents for damage. If there is damage, contact the delivery company and Teledyne ISCO (or its agent) immediately.

If there is any evidence that any items may have been damaged in shipping, do not attempt to install the unit. Please contact Teledyne ISCO (or its agent) for assistance.

When you unpack the system, check the items against the packing list. If any parts are missing, contact the delivery company and Teledyne ISCO's Customer Service Department. When you report missing part(s), please indicate them by part number. In addition to the main packing list, there may be other packing lists for various sub-components.

It is recommended that you retain the shipping cartons as they can be used to ship the unit in the event that it is necessary to transport the system. Please complete the registration card and return it to Teledyne ISCO.

1.6.1 Protective Window Cap Leave the protective window cap in place until the sensor is ready to be installed.

Before installation, remove the cap. The sensor will not be able to measure velocity with the cap in place. Retain the cap for use during cleaning, storage, or shipment, to protect the laser window from damage.

Be sure the protective window cap is installed during cleaning, storage, or shipment.



Figure 1-2 Remove protective window cap before installation

TIENet[®] 360 LaserFlow Ex[®] Velocity Sensor

Section 2 Preparation and Installation

2.1 Safety

Before installing, operating, or maintaining this equipment, it is imperative that all hazards and preventive measures are fully understood.

2.1.1 Site Conditions Components are often installed in confined spaces. Some examples of confined spaces include manholes, pipelines, digesters, and storage tanks. These spaces may become hazardous environments that can prove fatal for those unprepared. These spaces are governed by OSHA 1910.146 and require a permit before entering.

The installation and use of this product may subject you to hazardous working conditions that can cause you serious or fatal injuries. Take any necessary precautions before entering a worksite. Install and operate this product in accordance with all applicable safety and health regulations, and local ordinances.



2.1.2 Installation in Hazardous Locations

Read all labels carefully before installing the equipment!

The Laserflow Ex device is ATEX-approved for use in potentially explosive atmospheres when specific conditions are met, as described in this section in reference to "X" Marking.

The LaserFlow Ex is Group II, Category 1G equipment for use in gas hazard zones 0, 1, and 2 (European standards), or Class I Division 1 (North American standards).

The braid-drain lead depicted in Figure 2-1 is normally bonded to earth through the Signature connector case terminals or conduit. The mounting bracket used with the LaserFlow Ex should be installed such that there is a conductive path from the LaserFlow Ex case to earth. The internal circuitry utilizes a ground connection to the conductive case.

Installation must be performed only by trained, qualified personnel.

Barriers or isolators required for certifiable safe installation are the responsibility of the user. Refer to the control drawings provided in Figures 2-9.

Use only non-sparking metal for US mounting hardware. Check with local authorities.

The mounting bracket is a potential isolated charge carrier. For classified hazardous locations, refer to section 12.2.4 and local authorities for installation requirements.

Do not coil the sensor cable; this will form an inductor and create a hazard. The cable should be kept as short as is practical. If necessary, use a serpentine loop (see figure at left) instead.

Serpentine loop

_	\square
\square	
\square	

2.1.3 Important Information Regarding "X" Marking The ATEX labeling on the serial tag of the LaserFlow Ex device includes a number ending in "X." The X marking indicates that there are specific conditions that must be met in order for the equipment to comply with intrinsic safety requirements. Refer to Figure 2-1 on the following page.

These specific conditions are as follows:

- The cable must be terminated in a manner suitable for the zone of installation.
- The physical spacing between the exposed ends of each insulated wire lead, and earth ground and other IS circuits, must be such that the equipment is isolated up to 500V, and to 1500V for non-IS circuitry.

2.1.4 Electrical Always refer to the electrical values listed at the bottom of the LaserFlow Ex serial tag when connecting associated apparatus (i.e., power supply, network interface, etc.).

This labeling indicates the maximum input voltage (Ui), maximum input current (Ii), and maximum power (Pi) that can be present at the specified terminals without invalidating intrinsic safety.

The power supply parameter allowances *must exceed* maximum internal capacitance (Ci) and the maximum internal inductance-to-resistance ratio (Li/Ri) of the LaserFlow Ex device and cable. These parameters are established on the control drawing Figure 2-1.

2.1.5 Ambient Environment Installation in designated hazardous areas must fall within the temperature range of -10 to +60°C, as specified on the serial tag labeling.



Figure 2-1 Wiring diagram



Figure 2-2 LaserFlow Ex control drawing



Figure 2-3 LaserFlow Ex control drawing

- 2.2 Sensor Installation Considerations
 Measurement accuracy can be affected by a number of site factors that should be taken into consideration when selecting the location for the sensor.
 These factors may affect the laser velocity or the ultrasonic level, or both.
 If the laser velocimeter or ultrasonic transducer cannot obtain a valid reading at any measurement point, an asterisk (*) will appear next to the displayed reading, indicating there is an error.
 - **2.2.1 Ultrasonic Beam Angle** The ultrasonic level transducer has a 10° beam angle (5° from center line), forming a cone in which the apex is the transducer. The transducer can only detect surfaces within this cone.

10° 5°

Figure 2-4 Ultrasonic level sensor beam angle

The beam widens as distance to the flow stream increases. If the beam is too wide, the sensor may pick up signals from unwanted surfaces, such as the walls of the channel. Narrow channels can result in false echoes and incorrect level readings from the walls and sides of the channel. False Echo's can be minimized by using adjusting the minimum and maximum ultrasonic blanking distance.

2.2.2 High Water Levels In manhole installations where the level may exceed one-half of the full pipe, but less than full pipe, mount the sensor as near as possible to the midpoint between the entrance and exit to measure over the least turbulent flow. Where the level may exceed full pipe, the sensor should be mounted as close as possible to the flow entrance with the bottom of the sensor level with the top inner surface of the inlet pipe.

2.2.3 Submersion and Fouling Fouling Fouling Fouling by grease or solids can cause the LaserFlow Ex sensor to malfunction. The LaserFlow Ex is sealed, so unless it is exposed to corrosive substances, submersion of 2 meters, up to 72 hours will not harm it. Upon retrieval from submersion, ensure that the surfaces of the laser window and ultrasonic sensor are clean. Cleaning instructions are provided in Section 5.

2.2.4 Humidity	Conditions of extremely high or low humidity affect the speed of sound. To minimize this effect place the sensor as close as pos- sible to the flow stream.
2.2.5 Surface	Solids, foam, oil, and turbulence can absorb or scatter the ultra- sonic and laser signals, causing errors in detection. Foam or oil on the surface of the stream can also produce false level readings.
2.2.6 Temperature	Changes in ambient temperature significantly affect the velocity of sound. If ambient temperature changes rapidly, there may be a delay before the temperature sensor of the ultrasonic transducer can activate temperature compensation. Compensation is based on sensor temperature, to minimize the effect of air temperature gradients place the sensor as close as possible to the flow stream.
	✓ Note
	If the sensor is installed outdoors in direct sunlight, use a sun- shade to prevent heating of the sensor housing.
2.2.7 Waves	Waves on the surface of the flow stream can scatter the ultra- sonic signal, causing erroneous readings or total loss of signal. The flowmeter software rejects occasional readings that deviate substantially from normal.
2.2.8 Wind	Strong winds can reduce the strength of the ultrasonic return echo. To minimise effect, place the ultrasonic level measurement as close as possible to the flow stream.
2.3 Installation Checklist	Prior to installing the system, ensure that you have all supplies and site information readily available.
	To assist you in this preparation, this manual includes the <i>Installation Checklist</i> , page B-1. Teledyne ISCO recommends that you print this appendix and fill in the relevant information.
2.4 Connecting the Cable	The LaserFlow Ex cable will have one of two different connector types:
	• Unterminated for the TIENet Barrier
	Noto
	The TIENet Barrier connects to the Signature and the 2160 module.
2.4.1 Cable Connection:	LaserFlow Ex must connect to the TIENet Barrier. For more

information, see the TIENet Barrier Installation Guide.

TIENet Barrier

2.4.2 Cable Connection: Connect the LaserFlow Ex sensor to the Signature through the TIENet Barrier.

Refer to the Signature flowmeter manual for instructions on accessing the instrument's interior components.



Figure 2-5 Signature connected with the TIENet Barrier

Before proceeding, ensure that the flowmeter has been disconnected from mains power.

Mote

The following steps include instructions for installing cord-grip fittings. Some applications may use user-supplied $^{3}/_{4}$ " ID conduit for cable routing.

1. Remove one of the 6-position plug-in terminal strip connectors from the case board.



Figure 2-6 TIENet device terminal strips

2. If using a cord-grip fitting, install the cable nut in the appropriate opening on the bottom of the Signature enclosure, securing it to the wall with the lock nut (concave side facing wall).



Figure 2-7 Installing cable with a cord-grip fitting

- 3. Feed the TIENet device cable end through the sealing nut and seal and through the cable nut. Lightly tighten the sealing nut, just enough to hold the cable in place while installing the connector.
- 4. Attach the wire ends to the terminal strip as shown in Figure 2-8), then press the terminal strip back down into its socket on the case board, as shown in Figure 2-9, ensuring no wire connections are strained. Gently tug each wire when finished, to verify secure connection to the screw terminals.

Mote

The SHIELD wire is the bare drain emerging from the foil shield around the YELLOW and BROWN wires. The BRAID-DRAIN wire is the bare drain emerging from the surrounding braided shield inside the cable jacket. It is not necessary to prevent the two braids from coming into contact with each other.



Figure 2-8 TIENet device terminal connections





Figure 2-9 Attach wired terminal strip to case board socket

5. (Optional) Insert the reference tubing into the REF AIR port on the case board, pushing it down inside the silicon tubing. **Take precaution not to bend or kink the reference tubing.**



Figure 2-10 Insert the cable reference tubing into the case board reference port

6. Gently tug the cable downward to remove any slack within the enclosure, taking care not to put any stress on the connections.

7. Tighten the cord grip sealing nut (Figure 2-11).



Figure 2-11 Position and secure the cable

If using conduit instead of the cord-grip fitting, the conduit must be sealed to prevent harmful gases and moisture from entering the Signature enclosure. Failure to seal the conduit may reduce equipment life.

8. Close the front panel and fasten with the two Phillips screws.

2.4.3 Remote Ultrasonic Cable Connection: 310 Ultrasonic Sensor 1. Prepare the LaserFlow Ex connector receptacle by removing the cap (press down on the spring clip and pull out the cap).



Figure 2-12 Preparing the LaserFlow Ex connector receptacle

- 2. Remove the stainless steel cap from the 310 ultrasonic plug and push the protective caps from the LaserFlow Ex module and ultrasonic together.
- 3. Aligning the pins on the 310 ultrasonic plug with those in the connector receptacle, push the ultrasonic plug into the receptacle until the spring release "clicks".



Figure 2-13 Secure caps and connect the 310 ultrasonic plug to the LaserFlow Ex

To be certain that the connectors are locked, lightly pull on the cable connector; the cable should be held in place by the spring release clip.

2.5 Sensor Installation Tools and Requirements Tools and Requirements Tools and Requirements The Signature flowmeter or 2160 LaserFlow Module does not have to be mounted near the flow stream. The flowmeter can be installed at a convenient, protected location and the sensor cable can be routed through user-provided conduit back to the flowmeter.

Proper installation of the LaserFlow Ex is critical for accurate measurement.

- **2.5.1 Tools Required** See Appendix B.2 Equipment and Recommended Tools.
- 2.5.2 Sensor and Mounting Equipment Dimensions

g Complete mounting assembly dimensions are provided in Figures 2-14 through .

Refer to the appropriate drawing(s) when planning the installation and adjusting the mounting hardware.



Figure 2-14 Overall dimensions including wall mounting hardware (part 1)



Figure 2-15 Overall dimensions including wall mounting hardware (part 2)

2.5.3 Sensor Positioning and Requirements



Center of the pipe





Distance from sensor tip to laser beam exit point (vertex of 45° angle)

1 The figure on the left shows constants that serve as reference points when planning the positioning of the sensor.

Figure 2-16, shows a typical LaserFlow Ex manhole installation.

For proper function, the requirements listed here must be followed exactly.

Requirements:

- Permanent Installation: Install the wall bracket perpendicular to the x-axis.
- Always center the LaserFlow Ex (and middle laser beam) relative to the pipe walls, and always use the attached circular bubble level for vertical alignment.
- Mount the LaserFlow Ex sensor with the bottom parallel with the water surface.
- Align the bottom of the LaserFlow Ex with the top of the inside wall of the inlet pipe, and as close as possible to the pipe mouth without obstructing the laser. To accomplish this, refer to the figure at left, Figure 2-16 on the next page, and the following important figures:
 - The point at which the laser exits the sensor mouth is 3.3" (8.4 cm) from the front tip of the sensor, or the center of the opening.
 - The distance from the bottom of the LaserFlow Ex sensor to the center of the coupling tube is **10.375**" (**26.35 cm**).
 - The laser beam exits the sensor mouth at a **45° angle**.

(If the sensor bottom is parallel with the water surface, the laser beam will also strike the water surface at a 45° angle.)



Figure 2-16 Typical manhole installation

2.6 Wall Mounting Kit

For wall mounting, identify the components listed in Figure 2-17 and Table 2-1, and perform the steps that follow. Order numbers for parts and fasteners are provided in Appendix A.



Figure 2-17 Wall mounting kit (Numbers correspond with Table 2-1)

Table 2-1 Wall Mounting Kit	
Item (Callout #)	Description
1	Tube Coupler (short)
2	Tube Coupler (long)
3	Bottom Wall Mount Angle Bracket (adjustable)
4	Mounting Shaft
5	Sensor Carrier
	SST Anchor Stud Assembly & Spring Lock Washers (for fastening brackets to wall)
2.6.1 Wall Mount Installation

Refer to the dimensions and requirements in Figure 2-18 while performing the following steps.

🗹 Note

Stud anchors for concrete are provided in the mounting kit. It is recommended to drill a hole 2" (5.08 cm) deep, leaving 1" (2.54 cm) of the stud exposed.

- 1. Bolt or anchor the bottom angle bracket to the wall.
- 2. Slide the mounting shaft into the bottom angle bracket and bolt or anchor the mounting shaft to the wall.
- 3. Insert either the long or short tube coupler into the hole formed by the vertical clamp. Adjust the clamps to the desired height and cross-tighten the four bolts evenly until the clamp and tube coupler are firmly attached.



Figure 2-18 Wall Mount: Vertical clamp and vertical clamp with tube coupler inserted



Figure 2-19 Wall Mount: Sensor carrier installed on tube coupler

Mote

After initial installation and sensor alignment, the remaining steps are often possible to perform from above ground, with the optional sensor retrieval arm.

If lowering the LaserFlow Ex from above ground, ensure that it does not become dislodged while being lowered, possibly endangering any personnel who may still be below ground. 5. Lower the LaserFlow Ex sensor onto the mounting bracket between the front and rear alignment tabs, with the two mounting block grooves resting on the two carrier arms. The sensor can be installed on the carrier facing inward or outward, depending on installation requirements.



Figure 2-20 Wall Mount: Place the sensor on the carrier

- 6. Turn the locking handle clockwise until it locks the sensor in place.
- 7. Using the bubble level on top of the sensor as a guide, adjust the carrier by loosening the appropriate bolts in the sensor carrier clamp so that the bubble in the level falls within the concentric rings.
- 8. Turn the laser on to make final adjustments so that the laser beam hits the flow stream at the exact center of the pipe (refer to Section 3.4 for Signature or Section 4.3 for 2160).

Note

Additional assistance in adjusting the sensor's position may be obtained by activating and observing the 360 X-Axis (roll) and 360 Y-Axis (pitch) parameters.

9. Following final adjustments, ensure that all mounting bracket fasteners are tightened.

2.7 Optional Sunshade The sunshade is an optional accessory for use when the LaserFlow Ex sensor is installed in an outdoor location in direct sunlight. The purpose of the sunshade is to prevent sunlight from striking the case of the sensor directly and heating it to a higher temperature than that of the surrounding air.

This heating, caused by the absorption of sunlight, should be avoided, as it introduces an error factor into the flowmeter's level calculations.

- 1. Loosen the four tee knobs (two on each side of the sunshade) and slide the two adjustable mounting blocks to the rear of the slots on each side of the sunshade.
- 2. Position the sunshade on top of the LaserFlow Ex sensor mount and slide the sunshade toward the rear until the four stationary mounting blocks (two on each side of the sunshade) fit under the two front alignment tabs of the LaserFlow Ex sensor carrier. See Figure 2-21.



Figure 2-21 Mounting the sunshade

3. Slide the two adjustable mounting blocks (connected to the tee knobs) until they fit under the rear alignment tabs of the LaserFlow Ex sensor carrier. See Figure 2-21.



 $Figure\ 2\text{-}22\ Mounted\ sunshade$

4. Tighten the four tee knobs.

2.8 Remote TIENet Model 310 Ultrasonic Level Sensor

TIENet[®] 360 LaserFlow Ex[®] Velocity Sensor

Section 3 Setup with Signature® Flowmeter

The LaserFlow Ex velocity sensor is compatible with both the Teledyne ISCO Signature flowmeter and the Teledyne ISCO 2160 LaserFlow Module. For 2160 setup instructions, refer to Section 4. For complete information about the Signature flowmeter, refer to the Signature flowmeter user manual. 3.1 Configuring the To configure the Signature flowmeter for operation with the System LaserFlow Ex sensor, press the "Menu" button (| **B** |) to access the top menu, and then select "Hardware Setup". For all TIENet devices including the LaserFlow Ex sensor, select "Smart Sensor Setup (TIENet)". 3.1.1 Updating the Device When the LaserFlow Ex sensor has been physically added to the List system, select "Perform Scan" so that the flowmeter detects it. When the scan is complete, the LaserFlow Ex sensor (model number 360) appears in the list of connected devices, ready to be configured with the steps shown in Figure 3-2. M Note From the Hardware Setup menu, "Configure Measurements" refers to defining and selecting the parameters for each connected device. The LaserFlow Ex sensor parameters are: **360 Distance** – Distance between the bottom of the **360 Level** – Level of the flow stream surface sensor and the surface of the flow stream (refer to Section 3.2.2). **360 Velocity –** Average velocity of the flow stream **360 Case Temperature –** Internal temperature of the LaserFlow Ex sensor housing **360 Laser Temperature –** Temperature of the **360 X-Axis** – Tilt about the 'x' axis (roll) laser assembly 360 Y-Axis - Tilt about the 'y' axis (pitch) **360 Laser Diode Current –** Current draw of the laser diode 360 Ultrasonic Signal - Strength of the ultrasonic 360 Temperature - Temperature of the window return echo 360 Sense Voltage - Measurement of window 360 Air Temperature - Temperature of surrounding clarity (under 100 mV) -(ambient) air **360 Input Voltage –** TIENet voltage measured by 360 Doppler Power - Strength of the laser Doppler the LaserFlow sensor signal for velocity

The name of any parameter can be customized by highlighting it

and pressing the "**Enter**" button () to display the character grid. Navigate the grid using the arrow keys. Select characters by pressing the "**Enter**" button and clear characters by pressing

the **"Delete**" button ().

36	60	Di	st	an	ce									
D	one		Ca	nce										
A	В	С	D	Ε	F	G	Н	Ι	J	К	L	Μ	Ν	
Ο	Ρ	Q	R	S	Т	U	V	W	Х	Y	Ζ	а	b	
С	d	е	f	g	h	i	j	k	Ι	m	n	0	р	
q	r	S	t	u	V	W	X	У	Ζ		/	•	!	
@	#	\$	%	^	&	*	()	_	_	+	=	<	
>	?	,	•											♥

Figure 3-1 Character grid



Figure 3-2 Menu Tree: LaserFlow Ex Configuration

3.2 Measurement Setup

From Measurement Setup (Figure 3-3), select Level Input Setup to define the blanking distances and Velocity Input Setup to set velocity direction and access advanced settings.

Mote

Refer to the Signature user manual for information about Flow Rate Input Setup and Volume Input Setup.



Figure 3-3 Measurement Setup: Sensor input settings

3.2.1 360 Level

The **Minimum Blanking Distance** is the distance from the bottom of the sensor to the liquid surface at the highest expected level. Depending on the elevation of your sensor, this value may be increased to help ensure that echoes read by the flowmeter come only from the surface of the flow stream, and not off the walls or sides of the channel.

The **Maximum Blanking Distance** is the distance between the bottom of the sensor and the bottom of the channel (i.e., zero level). A larger value than calculated can be entered.

If using the LaserFlow Ex module with the 310 remote ultrasonic sensor and horizontal sensor mounting bracket, the maximum blanking distance is the distance between the bottom of the mounting bracket and the bottom of the channel.



Figure 3-4 Blanking distance for LaserFlow Ex with built-in sensor or with remote ultrasonic sensor

3.2.2	360 Velocity	When the Measure Positive Velocity only option is selected, the LaserFlow Ex will not attempt to determine flow direction.
3.2.3	LaserFlow Ex Velocity Advanced Settings	The LaserFlow Ex Advanced Settings are pre-programmed into the sensor. However, if your application requires any custom configuration, the Advanced button opens the Advanced settings window (refer to Figure 3-5).
		Input Velocity Coefficients – The relationship of the three Input Velocity Coefficients A, B and C can be expressed as:
		$\overline{V} = A \; (offset) + B^*(Measured \; Velocity) + C^*(Measured \; Velocity)^2$
		Coefficient A is an additive offset value to correct the Measured Velocity for any additive bias. The value for A must be expressed in units of meters/second. The default is "0".

Coefficient B is a multiplicative scalar for correcting the Measured Velocity for any linear multiplicative bias. The value for B is unitless. The default is "0.9".

Coefficient C is another scalar to correct the Measured Velocity for any nonlinear bias. The value for C must be expressed in units of seconds/meter, so that the resulting value for the Reported Velocity Reading will be in units of meters/second. The default is "0".

Spectral Averages – The value for Spectral Averages may be used to reduce sampling time and increase Doppler power under certain flow conditions. The default is "5000". If the flow is consistently turbulent or erratic and causing low Doppler power or velocity dropouts, enter a lower value, such as 3000. This will decrease sampling time and reduce noise in the Doppler signal caused by fluctuating velocity in the flow stream.

Re-home Count – For testing purposes only. For more information, contact Products Support Specialist Group (PPSG).

Adaptive Focus – Adaptive Focus enables the LaserFlow Ex module to scan above and below the standard focus point, then adjust the focus to the point with the best signal strength. To enable Adaptive Focus functionality, select the "**Adaptive Focus**" box.

Positive Downstream – Select the "**Positive Downstream**" box when the LaserFlow Ex sensor is pointed downstream. This selection reverses the sign on velocity readings such that positive velocity values indicate the direction of flow is in the same direction as the laser beam.

Maximum Distance – LaserFlow Ex (X0 hardware version) does not support directional velocity measurements.

Maximum Velocity – LaserFlow Ex (X0 hardware version) does not support directional velocity measurements.

Steep Slope LaserFlow Ex Focusing – If the pipe is on a slope greater than 1%, select the **"Enable Slope Setting"** box. By default, this option is disabled.

Parallel to Channel Slope – If the sensor is parallel to the channel slope, select "**Parallel to Channel Slope**". Measure from the front of the sensor carrier to the bottom of the channel. Then measure from the back of the sensor carrier to the bottom of the channel. Ensure the distance is equal. Adjust the sensor carrier as necessary. By default, this option is enabled when the "Enable Slope Setting" box is selected. See Figure 4-11 in Section 4.

Slope Percentage – If the slope of the pipe is known, mount the sensor level with the Earth, using the bubble level mounted on the top of the sensor and then enter the Slope Percentage in the field. By default, this option is disabled when the "Enable Slope Setting" box is selected. A positive slope value is used when the laser beam is pointed upstream. See Figure 4-12 in Section 4. **Optical Clarity** – Sense voltage detects fog on the window of the LaserFlow Ex sensor. When the sense voltage is greater than 150 mV, the defogger is activated. The defogger is enabled from 1 to 5 minutes, depending on the severity of the fog.

Mote

In locations with severe fogging potential, Teledyne ISCO recommends increasing battery capacity or monitoring the site more frequently.

To enable Optical Clarity, select "**Active**". To disable Optical Clarity, select "**Passive**". The default is "Active".

Remote Distance Measurement – The Remote Distance Measurement options are active only when the LaserFlow Ex module is connected to the TIENet 310 remote ultrasonic sensor.

• Be sure defaults are added for integral 310 Ex ultrasonic level sensor.

Advanced	
V	
Warning: Any changes to the following data can adversely affect the performance of this Instrument! Select BACK to cancel or NEXT to continue.	
A + (B * v) + (C * v ²) Input Velocity Coefficients	
A (default=0): 0 m/s	
B (default=0.9): 0.9	
C (default=0): 0 s/m	
Spectral Averages 5000 (default=5000):	
Re-home Count (default=100): 100	
Start Bin: 5	
Stop Bin: 1020	
Max Focus Depth: 6 in	
Min Doppler Power: 1000 in	
Focus Learning Algorithm	
Peak Detect	
Adaptive Focus	
Kemote Distance Measurement	For use with the
LaserElow Distance to Bottom in	remote 310 ultrasonic
Horizontal Mount	level sensor.
LaserFlow Directional Velocity	
☐ Focus Downstream	
Maximum Distance:	
Maximum Velocity: 1 ft/s	
Steep Slope LaserFlow Focusing	
Enable Slope Setting	
Parallel to Channel Slope	
O Slope Percentage: %	
Optical Clarity	
 Active Passive 	

Figure 3-5 Measurement setup: Advanced settings for LaserFlow Ex sensor

3.3 360 Velocity Grid The 360 Velocity screen has a grid containing 15 possible measurement points. Use the Shortcuts > Adjust function to navigate to this screen (refer to Figure 3-6).

The measurement points are activated and deactivated with the arrow and Enter keys. To save the measurement settings, high-light Update and press Enter.

As the LaserFlow Ex begins to take readings, the grid becomes populated with a velocity reading and time stamp for each active measurement point (points where a valid reading could not be obtained will display the word "invalid").

Prior to operation, the LaserFlow Ex sensor must be set up for measurement using the 360 Velocity grid. Refer to Section 3.4.



Figure 3-6 360 Velocity grid

3.4 Sensor Positioning and Adjustment



3.4.1 Centering the LaserFlow Ex Sensor		Proper positioning of the LaserFlow Ex sensor is critical for optimal velocity measurement. In center position, the laser beam must strike the flow stream precisely in the center.				
		The beam automatically moves to the top center position.				
Laser On		Select Laser On and press Enter. This will keep the laser beam on continuously for 10 minutes or until Laser Off is selected, allowing the beam to be used for fine-tuning the sensor's position.				
		☑ Note				
		When sensor positioning is completed, securely tighten all mounting hardware.				
3.4.2	Laser Velocity Measurement Point Selection	Once the LaserFlow Ex sensor is installed over the flow stream, some installations may only require the center laser position for velocity measurement.				
		For installations requiring multiple measurement points, the next step is to determine which points will be used. To do so,				

Each point will display a velocity reading and time stamp, or "Invalid." Deselect "Invalid" and undesired points. The fewer points selected, the less time required to complete one velocity measurement.

activate all 3 points and wait for all of them to display their

readings. This process may take up to 2 minutes.

Select the 3	<u>360 Velocity</u>							
and click UPDATE.	Laser On	Laser Of	f Upd	ate				
	Measuremen	its are displaye	ed in [UOM].					
			 1.01 7/17/12 3:30:27 PM 					
			0.99 7/17/12 3:31:52PM					
			Invalid 🔳					
	360 Velocity	Y						
	Laser On Laser Off Update							
	Measurements are displayed in [UOM].							
Deselect invalid (and undesired) points and click UPDATE			 1.01 7/17/12 3:30:27 PM 					
CIDAIL.			 0.99 7/17/12 3:31:52PM 					

Figure 3-7 Selection of velocity measurement points



Once the LaserFlow Ex sensor is installed over the flow stream, measure the present liquid level from the bottom of the channel (if there is a difference between the bottom of the channel and zero level, save this value for reference in flow calculation) and enter this value for Level, under Adjust options. Then highlight **Adjust** and press Enter to confirm.

From this screen, you can also update the display to show the current level of the stream.

Mote

Level adjustment of a newly installed and activated sensor should be performed only after the sensor is allowed to stabilize under site conditions (allow approximately one hour per 10 °F difference between storage and operating environments).



Figure 3-8 Ultrasonic level adjustment



E-mail: iscowatersupport@teledyne.com

TIENet[®] 360 LaserFlow Ex[®] Velocity Sensor

Section 4 Setup with 2160 LaserFlow Module

The LaserFlow Ex sensor is compatible with both the Teledyne ISCO 2160 LaserFlow Module and the Teledyne ISCO Signature flowmeter. For Signature setup instructions, refer to Section 3.

The 2160 module is programmed and set up using Teledyne ISCO Flowlink® software. This section of the manual describes activation of connected sensors, and basic LaserFlow Ex.

This section of the manual assumes the 2160 site is already configured in Flowlink, and the 2160 module is connected to Flowlink. Detailed Flowlink instructions are available in the Flowlink Windows Help and also in the Flowlink software user manual. For complete information about the 2160 LaserFlow Module, refer to the 2160 LaserFlow Module Installation and Operation Guide.

4.1 Activating Connected Sensors To add an available (connected) LaserFlow Ex sensor and activate in Flowlink, select the **TIENet** tab (Figure 4-1), then highlight the appropriate LaserFlow module 2160 module, and click the "**Configure**" button.

2100 Series Site	
Site: 2100 Series Site Jump to measurement tab >>	09:29 AM - Connected
Site Info Devices Measurements Data Combined Flow Alarms Wireless Power Control ADFM Mor	dbus Modem TIENet
2160 LaserFlow Module (2160)	Configure
Disconnect (F2) Retrieve Data (F8) DEFAULT Graph (F3) Apply (F9)	Cancel 🦻 Help

Figure 4-1 Activate connected sensors in Flowlink

A box is displayed, listing active and available TIENet Devices. Click the "**Scan**" button to detect any newly connected LaserFlow Ex or 350 Area Velocity sensors. Devices will appear in the Available TIENet Devices pane.

Highlight the appropriate device(s) and click the "**Add**" button to activate. Active TIENet devices will appear in the Active TIENet Devices pane. Click the "**OK**" button.

	Model	Device Name	Firmware Rev
1	360	Isco LaserFlow Sensor	2.0.30
R ailable TIEI	emove		
#	Model	Device Name	Firmware Rev
2	350	Isco Area-Velocity Sensor	1.9.310
	Scan Add		

Figure 4-2 Activating connected sensors in Flowlink

4.2 Measurement Display and Settings

The **Measurements** tab in the Site window lists the data types being measured by the 2160 module and displays real-time measurements.

🔚 2100 Series Site					
Site: 2100 Series Sit	te		Jump to measurement tab >>	03:26 PM -	Connected
Site Info Devices Meas	surements Data 360 Lr	evel Alarms Wirele	ss Power Control ADFM Modb	us Modem TIENet	
	1 1				
- Modules	lau ito magauramanta				
	lay its measurements.				
2160 LaserFlow Modul	e				
Click on a data label to a					
LICK on a data label to se	st its properties	- Flaur bit a dula			
Module Name: Elow Bate	2160 Las 234 845	app			
Total Flow	204.040 421966	gpin			
Input Voltage	421300	yai volts			
360 Distance	0.191	m			
360 Level	0.400	m			
360 Velocity	0.665	ft/s			
360 X-Axis	0.525	Deg			
360 Y-Axis	44.894	Deg			
360 Ultrasonic Signal	97.255	%			
360 Doppler Power	75426.0	Gen			
Disconnect (F2)	Retrieve Data (F8)	DEFAULT Graph (F	3) 🖌 Apply (F9)	X Cancel	🏆 Help

Figure 4-3 Measurements tab: Displays real-time measurements

To select and configure any parameter for your connected devices, click the "**Jump to measurement tab**" button at the top of the Site window and hover over the 2160 LaserFlow Module. Explanations for the listed measurements are provided in Figure 4-4.

		×
Jump to measurement tab >>	09:45 AM - Connected	
LaserFlow Module	•	
Flow Rate	360 Distance	360 Laser Diode Current
Flow Rate 2	Distance between the bottom of the sen-	Current draw of the laser diode
Total Flow	sor and the surface of the flow stream.	
Total Flow 2	360 Level	360 Ultrasonic Signal
Input Voltage	Level of the flow stream surface	Strength of the ultrasonic return echo
360 Distance	360 Velocity	Sense Voltage
360 Level	Average velocity of the flow stream	Measurement of window clarity (under
360 Velocity	Average velocity of the now stream	100 mV)
360 Case Temperature	360 Case Temperature	360 Air Temperature
360 Laser Temperature	Internal temperature of the LaserFlow Ex	Temperature of surrounding (ambient)
360 X-Axis	sensor housing	air
360 Y-Axis	360 Laser Temperature	360 Doppler Power
360 Laser Diode Current	Temperature of the laser assembly	Strength of the laser return Doppler
360 Ultrasonic Signal		signal
360 Sense Voltage	360 X-Axis	360 Window Temp
360 Air Temperature	Tilt about the 'x' axis (roll)	Temperature of the window
360 Doppler Power	360 Y-Axis	360 Input Voltage
360 Window Temp	Tilt about the 'v' axis (pitch)	TIENet voltage measured by the
Combined Flow		LaserFlow sensor

Figure 4-4 Drop down list of measurements for 2160 Module

Click on any parameter on the Measurements tab or in the Jump to Measurements tab list to open a dedicated tab to view details or set up data storage.

To prevent a parameter from being displayed on the Measurements tab, select the **Hide in Measurements** box.

The settings for level and velocity input are defined on their respective tabs in Flowlink. To save any changes made to the settings, click the "**Apply**" button.



The **Measurement** field displays the most recent level reading.

Once the LaserFlow Ex sensor is installed over the flow stream, measure the present liquid level from the bottom of the channel (if there is a difference between the bottom of the channel and zero level, save this value for reference in flow calculation). Enter this value in the Adjust level field. After the "**Apply**" button is clicked, the level you entered will appear in the Measurement field.

🗹 Note

Level adjustment of a newly installed and activated sensor should be performed only after the sensor is allowed to stabilize under site conditions (allow approximately one hour per 10 °F difference between storage and operating environments).

E 2100 Series Site	
Site: 2100 Series Site Jump to measurement tab >>	10:43 AM - Connected
Site Info Devices Measurements Data 360 Level Alarms Wireless Power Control ADFM Modbus Moder	m TIENet
Set up the measurement.	Set Up Data Storage
Module name: 2160 LaserFlow Module Measurement name: 360 Level Measurement: 0.472 <mark>meters</mark> ▼	Diagnostics Hide in Measurements
Level last adjusted: 2/19/2014 9:52:26 AM Adjust level: m Blanking Distance: m Min distance: 0.00 m Max distance: 3.50 m	
Disconnect (F2) Retrieve Data (F8) DEFAULT Graph (F3) 🖌 Apply (F9) 🗶	Cancel 🦿 Help

Figure 4-5 360 Level Measurement tab in Flowlink

The **Minimum Blanking Distance** is the distance from the bottom of the sensor to the liquid surface at the highest expected level. Depending on the elevation of the sensor, this value may be increased to help ensure that echoes read by the flowmeter come only from the surface of the flow stream, and not off the walls or sides of the channel.

The **Maximum Blanking Distance** is the distance between the bottom of the sensor and the bottom of the channel (i.e., zero level). A larger value than calculated can be entered.

If using the LaserFlow Ex module with the 310 remote ultrasonic sensor and horizontal sensor mounting bracket, the maximum blanking distance is the distance between the bottom of the mounting bracket and the bottom of the channel.



Figure 4-6 Blanking distance for LaserFlow Ex with built-in sensor or 310 remote ultrasonic sensor

4.2.2 360 Velocity The 360 Velocity measurement tab has a grid containing 3 possible measurement points. The measurement points are activated and deactivated by selecting or deselecting the appropriate check box. To save the measurement settings, click the "Apply" button (F9).

As the LaserFlow Ex begins to take readings, the grid becomes populated with a velocity reading and time stamp for each active measurement point (points where a valid reading could not be obtained will display the word "invalid").

Prior to operation, the LaserFlow Ex sensor must be set up for measurement using the 360 Velocity grid. Refer to Section 4.3 Sensor Positioning and Adjustment

2100 Se	eries Site				
Site: 2	2100 Series Site		Jump to measurement tab >>	> 11:19 AM - Connected	
Site Info	Devices Measurements Data	360 Velocity Alarms	Wireless Power Control ADFM	Modbus Modem TIENet	
Set up I	the measurement.			Set Up Data Storage	
	Module name: 2160 Laser Measurement name: 360 Velocit	Flow Module		Diagnostics	
	Measu <u>r</u> ement:	1.322 [feet/second	_	Hide in Measurements	
[Multipo	oint				
		☑ ^{1.2} 2/2	8 ft/s 20/2014 11:19:24 AM		I
	Γ		Г		I
Laser	on Laser off Advanced	I 🔲 Select All			
− Positiv P − Zero F	re Velocity ² ositive velocity true	-			
🗖 Set I	flow rate to zero if no velocity data				
Discor	nnect (F2) Retrieve Data (F8)	DEFAULT Gra	ph (F3) 🖌 🖌 Apply (F9)	🛛 🗶 Cancel 🛛 🥺 H	lelp

Figure 4-7 360 Velocity Measurement tab in Flowlink

4.2.3 Advanced Settings The LaserFlow Ex Advanced Settings are pre-programmed into the sensor. However, if your application requires the any custom configuration, the "**Advanced**" button opens the Velocity Coefficients window (refer to Figure 4-8).

		Velocity Coefficients			2
Confirm Warning: Any changes to the following data can adversely affect the performance of this instrument!	A	Input Velocity (A: 0 B: 0.9 C: 0		ts:	
Do you wish to proceed?	B— C—	Spectral Averages: Re-home Count: Start Bin: Stop Bin: Max Focus Depth: Min Doppler Power:	5000 100 5 1020 6 1000	in	
	D—	Pocus Learning Algorithm			
	E—	Remote Distance Measurement US Distance to Bottom: 0 LaserFlow Distance to Bottom: 0 Horizontal Mount LaserFlow Directional Velocity Focus Downstream Maximum Distance: 48			in
	F	Maximum Veloci	ity: Focusing	1	ft/s
	G—	Enable Slope S Parallel to Chai Slope Percenta	etting nnel Slope age:		%
	H—	Optical Clarity			
		🗸 ок	Cance	el	

Figure 4-8 360 Velocity Tab: Advanced settings

Velocity Coefficier	nts	×
Input Ve	locity Coefficients:	
A:	0	
В:	0.9	
C:	0	

A - Input Velocity Coefficients

Input Velocity Coefficients – The relationship of the three Input Velocity Coefficients A, B and C can be expressed as:

 $\overline{V} = A (offset) + B^*(Measured Velocity) + C^*(Measured Velocity)^2$

Coefficient A is an additive offset value to correct the Measured Velocity for any additive bias. The value for A must be expressed in units of meters/second. The default is "0".

Coefficient B is a multiplicative scalar for correcting the Measured Velocity for any linear multiplicative bias. The value for B is unitless. The default is "0.9".

Coefficient C is another scalar to correct the Measured Velocity for any nonlinear bias. The value for C must be expressed in units of seconds/meter, so that the resulting value for the Reported Velocity Reading will be in units of meters/second. The default is "0".

Spectral Averages:	5000

B - Spectral Averages

Re-home Count: 100

	C	- j	Re-	hom	e C	loun
--	---	-----	-----	-----	-----	------

Focus Learning Algorithm	
--------------------------	--

Adaptive Focus

D - Focus Learning Algorithm

Spectral Averages – The value for Spectral Averages may be used to reduce sampling time and increase Doppler power under certain flow conditions. The default is "5000". If the flow is consistently turbulent or erratic and causing low Doppler power or velocity dropouts, enter a lower value, such as 3000. This will decrease sampling time and reduce noise in the Doppler signal caused by fluctuating velocity in the flow stream.

Re-home Count – For testing purposes only. For more information, contact Environmental Products Support.

Focus Learning Algorithm – Adaptive Focus enables the LaserFlow Ex module to scan above and below the standard focus point, then adjust the focus to the point with the best signal strength. To enable Adaptive Focus functionality, select the **"Adaptive Focus"** check box.

-Remote Distance Measurement -		
US Distance to Bottom:	1	in
LaserFlow Distance to Bottom:	1	in
🔲 Horizontal Mount	,	

E - Remote Distance Measurement

Remote Distance Measurement – The Remote Distance Measurement options are active only when the LaserFlow Ex module is connected to the TIENet 310 remote ultrasonic sensor.

The **US Distance to Bottom** is the distance (e.g., inches) from the 310 remote ultrasonic sensor to the bottom of the channel. See Figure 4-9. Units of measurement are based on user settings.

Mote

When using the horizontal sensor mount bracket, the US Distance to Bottom is measured from the bottom tip of the horizontal sensor mount bracket to the bottom of the channel. See Figure Figure 4-10.

The **LaserFlow Ex Distance to Bottom** is the distance (e.g., inches) from the bottom of the LaserFlow Ex sensor the bottom of the channel. Units of measurement are based on user settings.

Select the "**Horizontal Mount**" check box if using the optional horizontal sensor mount bracket. See Figure 4-10.

Mote

Add default values for remote distance when integral.



Figure 4-9 Remote distance measurement with the 310 remote ultrasonic sensor



remote ultrasonic sensor and horizontal sensor mount bracket

LaserFlow Directional Velocity —		
Maximum Distance:	48	in
Maximum Velocity:	1	ft/s

F - LaserFlow Ex Directional Velocity

Steep Slope LaserFlow Focusing	
Enable Slope Setting	
Parallel to Channel Slope	
C Slope Percentage: %	

G - Steep Slope LaserFlow Ex Focusing **LaserFlow Ex Velocity –** The LaserFlow Ex Velocity options are active only when the Positive Velocity option is "false".

Select the "**Focus Downstream**" check box when the LaserFlow Ex sensor is pointed downstream.

Steep Slope LaserFlow Ex Focusing – If the sensor is on a slope greater than 1%, select the **"Enable Slope Setting"** check box. By default, this option is disabled.

If the sensor is parallel to the channel slope, select "**Parallel to Channel Slope**". Measure from the front of the sensor carrier to the bottom of the channel. Then measure from the back of the sensor carrier to the bottom of the channel. Ensure the distance is equal. Adjust the sensor carrier as necessary. See Figure 4-11. By default, this option is enabled.

If the slope of the pipe is known, mount the sensor level with the Earth, using the bubble level mounted on the top of the sensor and then enter the **Slope Percentage** in the field. A positive slope value is used when the laser beam is pointed upstream. See Figure 4-12. By default, this option is disabled.



Figure 4-11 LaserFlow Ex placement using Parallel to Channel Slope option





- Optional Clavity	
Optical Clarity	
Active	
C Passive	

H - Optical Clarity

Optical Clarity – Sense voltage detects condensation on the window of the LaserFlow Ex sensor. When the sense voltage is greater than 100 mV, the defogger is activated. The defogger is enabled from 1 to 5 minutes, depending on the severity of the fog.

Mote

In locations with severe fogging potential, Teledyne ISCO recommends increasing battery capacity or monitoring the site more frequently.

To enable Optical Clarity, click "**Active**". To disable Optical Clarity, click "**Passive**". The default is "Active".

Lass-Flave Handerson Davisian	-	0		
LaserFlow Hardware Revision	Δ2	62	C6	XO
Innut Velocity Coefficients:				
Δ.	0.0	0.0	0.0	0.0
B:	0.9	0.9	0.9	0.9
C:	0.0	0.0	0.0	0.0
Spectral Averages:	5.000	5.000	5.000	5.000
Re-home Count:	100	100	100	100
Start Bin:	15	7	7	7
Stop Bin:	1,020	1,020	1,020	1,020
Max Focus Depth:	0.1524 m	0.1524 m	0.1524 m	0.1524 m
Min Doppler Power:	1,000	1,000	1,000	1,000
Focus Learning Algorithm				
Peak Detect	Un-checked	Un-checked	Un-checked	Un-checked
Adaptive Focus	Un-checked	Un-checked	Un-checked	Un-checked
Remote Distance Measurement				
US Distance to Bottom	N/A	N/A	0.0 m	0.29765 m ^{note}
LaserFlow Distance to Bottom	N/A	N/A	0.0 m	0.0 m
Horizontal Mount	N/A	N/A	Un-checked	Un-checked
LaserFlow Directional Velocity				
Focus Downstream	Un-checked	Un-checked	Un-checked	Un-checked
Maximum Distance	1.2192 m	1.2192 m	1.2192 m	1.2192 m
Maximum Velocity	0.3048 m/s	0.3048 m/s	0.3048 m/s	0.3048 m/s
Steep Slope LaserFlow Focusing				
Enable Slope Setting	Un-checked	Un-checked	Un-checked	Un-checked
Parallel to Channel Slope	Checked	Checked	Checked	Checked
Slope Percentage	Un-checked	Un-checked	Un-checked	Un-checked
Optical Clarity				
Active	Checked	Checked	Checked	Checked
Passive	Un-checked	Un-checked	Un-checked	Un-checked

Table 4-1 Default Advanced Settings

Note 1 – If the LaserFlow Ex was used in a remote ultrasonic configuration and now will be used in the built in configuration, set the US Distance to Bottom value to 0.29765 m and the LaserFlow Distance to Bottom to zero.

4.3 Sensor Positioning and Adjustment	To set the initial level values, refer to Sections 4.2.1.
	CAUTION - CLASS 3R LASER RADIATION WHEN OPEN AVOID DIRECT EYE EXPOSURE ATTENTION - RAYONNEMENT LASER DE CLASSE 3R - EN CAS D'OUVERTURE EXPOSITION DIRECTE DANGEREUSE DES YEUX
	Image: Construction of the construc
4.3.1 Centering the LaserFlow Ex Sensor	Proper positioning of the LaserFlow Ex sensor is critical for optimal velocity measurement. In center position, the laser beam must strike the flow stream precisely in the center.
	The beam automatically moves to the top center position.
Laser on	Select the "Laser on" button and click the "Apply" button. This will keep the laser beam on continuously for 10 minutes or until the "Laser off" button is clicked, allowing the beam to be used for fine-tuning the sensor's position.

$\mathbf{\nabla}$	Note
-------------------	------

When sensor positioning is completed, securely tighten all mounting hardware.

4.3.2 Laser Velocity
Measurement Point
SelectionOnce the LaserFlow Ex sensor is installed over the flow stream,
some installations may only require the center laser position for
velocity measurement.

For installations requiring multiple measurement points, determine which points will be used. To do so, activate the 3 points and wait for all of them to display their readings. This process may take up to 15 minutes.

Each point will display a velocity reading and time stamp, or "Invalid." Deselect "Invalid" and undesired points. The fewer points selected, the less time required to complete one velocity measurement.

Select the "Select All" check box to activate the 3 points, then click the "Apply" button.



Deselect "Invalid" and undesired points, then click the "**Apply**" button.

		I.16 ft/s 2/21/2014 8:07:28 AM		
	Γ	Π		
		✓ 2.83 ft/s 2/21/2014 8:08:40 AM	Г	
Laser on	Laser off Advanced	🔽 Select All		

Figure 4-13 Selection of velocity measurement points

TIENet[®] 360 LaserFlow Ex[®] Velocity Sensor

Section 5 Maintenance and Optional Kits

5.1 Maintenance

The following tables are recommended maintenance checks to ensure proper operation. As site conditions may vary, increase the frequency of inspections as needed.

Table 5-1 Recommended Maintenance (Accessible Locations)		
Action	Recommended Frequency	Location
Check Ultrasonic level sensor for obstructions (e.g., spider webs, debris)	Monthly	On-site
Check Horn for obstructions (e.g., spider webs, debris)	Monthly	On-site
Ensure suitable alignment - check x-axis (roll) and y-axis (pitch)	Weekly	Via Flowlink application or Signature flowmeter
Check Doppler Power and assess historical trend	Weekly	Via Flowlink application or Signature flowmeter
Check Ultrasonic Signal and assess historical trend	Weekly	Via Flowlink application or Signature flowmeter

Table 5-2 Recommended Maintenance (Difficult-to-Access Locations)

Action	Recommended Frequency	Location
Check Ultrasonic level sensor for obstructions (e.g., spider webs, debris)	Every 6 months or following surcharge event	On-site
Check Horn for obstructions (e.g., spider webs, debris)	Every 6 months or following surcharge event	On-site
Ensure suitable alignment - check x-axis (roll) and y-axis (pitch)	Weekly	Via Flowlink application or Signature flowmeter
Check Doppler Power and assess historical trend	Weekly	Via Flowlink application or Signature flowmeter
Check Ultrasonic Signal and assess historical trend	Weekly	Via Flowlink application or Signature flowmeter

When firmware updates become available, they can be down- loaded from www.isco.com or via email from the factory.	
The TIENet device's firmware is updated via the USB port on the front panel of the Signature flowmeter. Step-by-step instructions for updating the firmware can be found in Section 2 of the Sig- nature user manual.	
The TIENet device's firmware is updated via the "Update Isco Instrument Software" tool from Flowlink for the 2160 module. Step-by-step instructions for updating the firmware can be found in the Help text of the update application.	
The LaserFlow Ex sensor's outer housing and ultrasonic trans- ducer can be cleaned with warm water, mild soap, and a soft, lint-free cloth. Do not spray water on the laser window; install the protective window cap prior to cleaning.	
Never use ordinary cloth or abrasives to clean the LaserFlow Ex as they may cause scratches.	
Be sure the protective window cap is installed during cleaning, storage, or shipment (refer to Section 1.6.1).	
Several procedures for maintenance and options require accessing the interior of the sensor by separating the nose piece from the body, and subsequent reassembly. Refer back to this section when performing these procedures.	
Disconnect power from the LaserFlow Ex sensor before opening the sensor housing.	
• #2 Phillips straight screwdriver less than 4" (right-angled if available)	
5.4.1 Removing the Nose Piece

The screws that attach the nose piece to the body are difficult to access with a straight screwdriver, being somewhat obstructed by the mounting block.

1. Remove the 6 large Phillips screws on the LaserFlow Ex nose piece, and separate the nose from the body. **Do not remove any other screws.**



Figure 5-1 Remove large screws and nose piece (3 on each side)

- 5.4.2 Replacing the Nose Piece
- 1. Fasten the sensor back together by cross-tightening the 6 large Phillips screws in diagonal order until the two sections are flush against each other.

When reinstalling all self-tapping screws, avoid stripping the plastic threads. First seat each screw in its hole and, with light downward pressure, rotate the screw counter-clockwise until it falls into its thread groove with a "click". Then tighten the screw.

2. If applicable, reinstall the mounting block, ensuring that both flat and split washers are included.



 $Figure \ 5-2 \ \ Location \ and \ orientation \ of \ cross-pins \ for \ mounting \ block \ installation$

5.5 Velocity Readings and the Laser Window Invalid or inconsistent velocity readings may indicate debris or moisture condensation on the window protecting the laser.

The laser window is crucial for focusing and should never be touched. Smudging or scratches can degrade the performance of the sensor. For these reasons, cleaning the window is NOT recommended unless absolutely necessary.

If cleaning must be performed, follow the instructions provided in Section 5.6.

 5.6 Cleaning the Laser Window
 The laser window is crucial for focusing and should never be touched. Smudging or scratches can degrade the performance of the sensor. For these reasons, cleaning the window is NOT recommended unless absolutely necessary.

Never touch the laser window. Never use ordinary cloth or water to clean the surface of the laser window.

 Pre-packaged, pre-IPA-moistened, single-use, lint-free tissue, such as Zeiss Lens Cleaning Wipes or Bausch & Lomb Sight Savers^{®1} Pre-Moistened Lens Cleaning

Items required for cleaning

• Kimwipes^{®2} dry tissues

Tissues.

• Rain-X®³ Original Glass Treatment

Never moisten the tissue with IPA or other solution *after* removing it from its package.

You must remove the nose piece to clean the window. Instructions for opening and reassembling the LaserFlow Ex nose piece are provided in Section 5.4 Accessing the LaserFlow Ex's Nose Piece.

Disconnect power from the LaserFlow Ex sensor before opening the sensor housing.

- 1. Remove the folded tissue from its package and use the corners to lightly brush any abrasive material from the surface.
- 2. Unfold the tissue and gently clean the surface with downward strokes only, **keeping the tissue between your finger and the glass at all times**.

- 2. Kimwipes® is a registered trademark of Kimberly-Clark Corporation.
- 3. Rain-X® is a registered trademark of Illinois Tool Works, Inc.

Procedure

^{1.} Sight Savers® is a registered trademark of Bausch & Lomb, Inc.

- Examine the window closely under good lighting from all directions to ensure there are no smudges, streaks, or film on the surface.
 If the window is smudged, streaked, or still dirty, get a fresh pre-packaged tissue and repeat.
- 4. Next, fold a clean, dry Kimwipe tissue four times to reinforce its thickness, and gently clean the window surface with downward strokes only, **keeping the tissue between your finger and the glass at all times.**
- 5. Examine the window closely under good lighting from all directions to ensure there are no smudges, streaks, or film on the surface.

If the window is smudged, streaked, or still dirty, get a fresh pre-packaged tissue and repeat.

6. Fold a fresh Kimwipe tissue as previously described and spray the closed end of it with Rain-X.



Figure 5-3 Cleaning the laser window: Moisten Kimwipe tissue w / Rain-X

- 7. Apply the Rain-X to the entire window surface using downward strokes only.
- 8. After allowing 30 minutes for the Rain-X treatment to dry, wipe the window with another dry Kimwipe tissue, as described in step 4.
- 9. Carefully examine the window as previously described, and continue polishing the surface with fresh dry tissues until no streaks or film are visible.

Reassemble the nose piece, following the steps provided in Section 5.4.2 *Replacing the Nose Piece*.

5.7 Installing the Remote TIENet 310 Ultrasonic Level Sensor

TIENet[®] 360 LaserFlow Ex[®] Velocity Sensor

Appendix A Replacement Parts

A.1 Replacement Parts Diagrams and Listings

Replacement parts can be purchased by contacting Teledyne ISCO's Customer Service Department.

Teledyne ISCO

Customer Service Department P.O. Box 82531 Lincoln, NE 68501 USA

Phone: (800) 228-4373 (402) 464-0231 FAX:(402) 465-3022

E-mail: isco.orders@teledyne.com

A.2 LaserFlow Ex Sensor 360 LaserFlow Sensor Replacement Parts



604367001

Replacement LaserFlow Mounting Handle Kit



604363014 Horn used on LaserFlow Sensor (black)



609004470 Replacement Small Parts Package Kit for LaserFlow

Vertical Mounting Bracket Kit



609004471 Replacement LaserFlow Vertical Mounting Components Kit for Permanent Wall Mounting



202100669 O-Ring (0.699 I.D., 0.079 Cross Section)



231115921 Hex Machine Screw (1/4-20 x 1-1/4 inch long)



604364037 Anchor Studs with Lock Washers used on LaserFlow Mounting Bracket

Horizontal Tube Coupler Parts

PHOTO NOT AVAILABLE

604363026

Coupling Tube used on LaserFlow Mounting Bracket

PHOTO NOT AVAILABLE

604363036

Extended Coupling Tube used on LaserFlow Mounting Bracket

PHOTO NOT AVAILABLE

605324154

24" Laser Mount Coupling Tube

Horizontal Mount Bracket Parts Kit



609004472

Replacement LaserFlow Horizontal Mounting Components Kit for Permanent Wall Mount

U Tube Mounting Bracket Parts

PHOTO NOT AVAILABLE

604364044 Mounting Alignment Tabs with Hardware Kit



231115921 Hex Machine Screw (1/4-20 x 1-1/4 inch long)

A.3 Wall Mounting Hardware

360 LaserFlow Sensor Temporary Mounting Kits



609004473

Replacement LaserFlow Temporary Mount Cargo Bar Clamp Kit



60-9004-474 Replacement LaserFlow Temporary Mount Kit For U Tube Clamp

A.4 Replacement Sensors

TIENet 360 LaserFlow Ex Sensor with Built-in Ultrasonic

LaserFlow Ex Sensor, 10m Unterminated	l Cable	Call Factory
LaserFlow Ex Sensor, 23m Unterminated	Cable	Call Factory
LaserFlow Ex Sensor, cut to length Unter	minated Cable	Call Factory

Includes TIENet 310 Ultrasonic Level Sensor

Excludes TIENet 310 Ultrasonic Level Sensor

A.5 Sensor Accessories

ctory
C

TIENet[®] 360 LaserFlow Ex[®] Velocity Sensor

Appendix B Installation Checklist

B.1 Introduction

This special appendix is to assist you in ensuring that you have all equipment, supplies, and site information readily available prior to going to site for installation.

Print these pages and fill out all relevant information.

Once you have established that all of the items listed here are on hand, take this printout to the site to assist in installation and setup.

B.2 Equipment and	□ LaserFlow Ex Sensor				
Recommended Tools	□ 2160 Module or Signature flowmeter				
	□ Flowlink 5.1 Software and Communication Cable				
	\Box Power source				
	□ Tape Measure				
	\Box Level				
	□ Laptop computer				
	Wall Mount Kit, if mounting on wall				
	o ⁷ /16" Open or Socket Wrench				
	o ⁹ /16" Open or Socket Wrench				
	o Hammer Drill				
	o ³ /8" Masonry Bit				
	o Hammer				
	□ Temporary Mount Kit, if application is temporary				
	o ⁷ /16" Open or Socket Wrench				
	Optional Sensor Retrieval Tool				
B.3 Site Information	1. Site Name:				
	2. Meter:				
	□ 2160 Module (Serial Number:)				
	□ Signature flowmeter (Serial Number:)				
	□ LaserFlow Ex Sensor (Serial Number:)				
	□ TIENet Barrier (Serial Number:)				
	3. Meter Location:				
	4. Channel Shape:				
	□ Round				
	\Box U-Shaped				
	□ Rectangular				
	□ Trapezoidal				

 \Box Elliptical

- 6. Number of Velocity Points:
- 7. Expected Level (m or ft) Minimum:

Maximum: _____

Average: _____

- 8. Expected Velocity (m/s or ft/s) Minimum: _____ Maximum: _____ Average: _____
- 9. Distance between bottom of sensor & flow at Maximum Level (m or ft) _____
- 10. Distance between bottom of sensor & channel bottom (m or ft): _____
- 11. Direction sensor is facing:
- □ Upstream
- \Box Downstream
- 12. Site IP Address: _____
- 13. Call-In Window Start: _____ Stop: _____

14. Server Push Address: _____

15. Software Revisions Flowlink: _____(Help > About Flowlink) LaserFlow Ex: _____(TIENet / Configure) 2160: _____(Device Tab) Signature: _____(Menu > Admin > Display Signature Information)

16. Data Storage Rate: _____

B.4 Recommended Essential Parameters	The following basic parameters are used in almost every mea- surement site.		
	In the 2160, parameters are activated in the Jump to Measurements tab.		
	In the Signature, parameters are activated by going to Hardward Setup > Configure Measurements.		
	360 Distance	360 Level	
	360 Velocity	360 X-Axis	
	360 Y-Axis	360 Ultrasonic Signal	
	360 Doppler Power	360 Case Temperature	
	360 Air Temperature	Flow Rate	
	360 Sense Voltage	For recommended parameters	
	After programming Retrieve	Data to download initial diagnostic	

B.5 Site Conditions LaserFlow Ex with Built-in Sensor: When using the LaserFlow Ex module with the attached sensor, never install the LaserFlow Ex in a free-flowing outfall or in a drop manhole (see Figure B-1).



data, to verify that this data will be available if/when needed.

Figure B-1 Do not install LaserFlow Ex with built-in sensor in a free-flowing outfall or in a drop manhole.

LaserFlow Ex with Remote Ultrasonic Sensor: When using the LaserFlow Ex module with the remote ultrasonic sensor, the LaserFlow Ex sensor can be installed in a free-flowing outfall or in a drop manhole.



Figure B-2 Correct setup when using the LaserFlow Ex module with remote ultrasonic sensor and horizontal mount bracket

Stream Level – The stream level should be the same at both the laser and ultrasonic measuring points.



Figure B-3 Placement of LaserFlow Ex with built-in sensor

Mote

If the stream level is less than 3" (7.62 cm) when using the LaserFlow Ex with built-in sensor, ensure the Adaptive Focus option is active Figure B-3.



Figure B-4 Placement of LaserFlow Ex with remote ultrasonic sensor

⊠ Note

If the laser and ultrasonic measuring points differ at the stream level by more than 3" (7.62 cm), the remote ultrasonic sensor must be used, Figure B-4.



Foam or Steam – Never install the LaserFlow Ex over foam or steam.

B.6 Sensor Positioning

Straight Runs – For best performance, place the sensor in the straightest possible run, at a minimum of 5 channel diameters downstream and 2 channel diameters upstream from a bend or divergence or convergence of channels.



Center of Pipe – Center the LaserFlow Ex (and middle laser beam) relative to the pipe walls.



Parallel w/ Flow – Install the LaserFlow Ex parallel with the flow.

Never install it at an angle, or perpendicular, to the flow.



TIENet[®] 360 LaserFlow Ex[®] Velocity Sensor

Appendix C Velocity Error Codes

C.1 Introduction	Erroneous flow data can result from a number of factors. The LaserFlow Ex system provides numbered error codes associated with the 360 Velocity data to assist in troubleshooting.			
	If using the 2160 LaserFlow Ex module, error codes are viewable using Teledyne ISCO Flowlink® software. If using the Signature flowmeter, error codes are viewable in the bottom panel of the display. Definitions of the error codes are provided in Table C-1. For further assistance, contact the factory.			
C.2 Importing Data Dump (.ddp) Files	Flow data can be downloaded from the Signature flowmeter ont a USB flash drive in the form of a .ddp (Data Dump) file.			
(Signature Only)	To download the data:			
	1. Connect a flash drive to the USB port on the front panel of the Signature flowmeter. From the USB Options menu, select Retrieve Data.			
	2. Select "All data" or specify a start date or date range, and press NEXT. The data will be stored on the connected flash drive in the "ISCO" folder.			
	3. Connect the flash drive to a computer with Flowlink installed.			
	4. Launch the Flowlink application.			
	5. Copy the file using one of the methods below:			
	a. Select File > Import. When the import window appears, browse to the folder containing the desired .ddp file. Select the file and click Open.			

b. Select "Signature Data Transfer" from the File menu and then browse to the appropriate folder.

File Item Actions	Database View I	Select files for	import				? 🔀
New Open Close Save	Ctrl+N Ctrl+O Ctrl+S	Look in:	DDP		•	← 🗈 💣 💷•	
Quick Connect RTD Transfer Signature Data Tra	F11	My Recent Documents	D0728.ddp D0746.ddp D1037.ddp D1042.ddp				
Import Export	CHUR	Desktop	D1111.ddp D1311.ddp D1342.ddp				
Print Preview Print Setup	Cui+P	My Documents	D1400.ddp D1430.ddp D1519.ddp				
Exit	Alt+F4	My Computer					
		1,4000	File <u>n</u> ame: Files of <u>t</u> ype:	D0728.ddp Data Dump Format (*.ddp)		•	Open Cancel

Figure C-1 Signature flow data: Selecting the .ddp file(s)

A progress window will appear, displaying the filename, site name, device type, number of data types in the site file, and progress of the download.

6. When the two progress bars have completed, click Done to close the window.

🖷 Import Progress			🖷 Import Progress 📃 🗖 🗙
т	OTAL	CURRENT	TOTAL CURRENT
File:	1	D0709.ddp	File: 1 D0709.ddp
Site:	1	350	Site: 1 350
Device:	1	Signature Meter	Device: 1 Signature Meter
Data Types:	0		Data Types: 13
Data Points Read: 2	74247		Data Points Read: 274247
Data Points Written: 20	04789		Data Points Written: 274247
Current File:			Current File:
Overall:			Overall:
Do	Cancel		Done Cancel

Figure C-2 Signature flow data: Importing the .ddp file

Upon completion, a new site file will appear in the Flowlink workspace.

C.3 Viewing Velocity Error	In order to view error codes for velocity readings:
Codes in Flowlink	1. In the Flowlink workspace, double-click the

1. In the Flowlink workspace, double-click the 360 Velocity data set. When the graph appears, click the Table View button.



2. When the table appears, click the Edit/View button.



Any error codes will appear in the 360 Velocity column following the words "No Data." Definitions of the error codes are provided in Table C-1.

Date/Time	360 Velocity(m/s)	Edited 360 Velocity(m/s)
10/4/2012 1:45:00 PM	0.621	0.621
10/4/2012 2:00:00 PM	0.601	0.601
10/4/2012 2:15:00 PM	2.251	2.251
10/4/2012 2:30:00 PM	2.154	2.154
10/4/2012 2:45:00 PM	No Data: 1	2.154
10/4/2012 3:00:00 PM	1.897	1.897
10/4/2012 3:15:00 PM	No Data: 1	0.694
10/4/2012 3:30:00 PM	5.195	5.195
10/9/2012 10:00:00 AM	No Data: 7 🛒	0.000
0/9/2012 10:15:00 AM	No Data: 7	0.000

Error codes

Figure C-3 Identifying error codes in the 360 Velocity data set

Table C-1Definitions of 360 Error Codes			
Error Code	Meaning	Possible Solutions	
1: Low Signal Power Error	No laser Doppler signal peak or sufficient strength is found. Mini- mum is 1000.	Ensure the protective window cap is removed. Refer to Section 1.6.1 Protective Window Cap.	
		Ensure the location of the laser is correct.	
		Verify the distance is 0 to 10 ft from the bottom of the sensor to the flow stream.	
		Ensure the Y-axis (pitch) is accurate (greater or equal to 45°).	
2: Flow Direction Error	An error occurred while determin- ing flow direction. This error dis- plays only if the "Positive Velocity" option is set to "true" in the Flow- link application.	If velocity is frequently below 0.1 m/s (0.3 ft/s), the LaserFlow Ex will not be able to determine the flow direction.	

Table C-1Definitions of 360 Error Codes			
Error Code	Meaning	Possible Solutions	
3: Ultrasonic Read/Level too Low Error	An error occurred during an ultra- sonic reading. This includes com-	Ensure the blanking distance is correct. Refer to Section 3.2 Measurement Setup.	
	munication errors with the ultrasonic sensor or the level is below the "minimum level for velocity" threshold.	Ensure the placement of the sensor is accurate. Refer to Section 2.5.3 Sensor Positioning and Requirements.	
		Verify there is no foam, steam, or extreme turbulence.	
4: Noisy Doppler Signal Error	The DSP detected a noise level in the doppler signal that is higher than the calibrated noise thresh- old.	Contact factory.	
5: Focus Error	An error occurred while focusing the laser.	Contact factory.	
6: Digital Signal Proces- sor (DSP) Communication Error	An error occurred during commu- nication with the DSP.	Contact factory.	
7: Sensor not seen	Communication failed between	Ensure the sensor is connected to the flowmeter.	
	flowmeter and sensor. This could be due to the sensor being dis-	Ensure the input voltage is 9V (minimum).	
connected, losing power, etc		Verify the battery is connected or charged.	

Table C-2Definitions of 350 Error Codes				
Error Code	Meaning	Possible Solutions		
1: Measurement Error	Unable to generate valid velocity data set.	Contact factory.		
3: Velocity Filter Error	An error occurred while setting the filter clock.	Ensure there are uniform flow conditions at sensor location.		
5: Velocity Gain Error	Unable to set gain after maximum attempts.	Ensure there is no debris on the sensor.		
6: Level too Low error	The absolute level is too low to	Place sensor in flow with at least 1" deep.		
	attempt velocity measurement.	Set storage of velocity to be secondary based on depth of 1".		
7: Timeout/Quality Error	Measurement timed out or did not meet measurement quality requirements.	Contact factory.		

TIENet[®] 360 LaserFlow Ex[®] Velocity Sensor

Appendix D Material Safety Data Sheets

This appendix provides Material Safety Data Sheets for the desiccant used by the TIENet 360 LaserFlow Ex Sensor.

Teledyne ISCO cannot guarantee the accuracy of the data. Specific questions regarding the use and handling of the products should be directed to the manufacturer listed on the MSDS.

SORB-IT® is a registered trademark of N. T. Gates Company.





MATERIAL SAFETY DATA SHEET -- September 28, 1998 SORB-IT[®]

Packaged Desiccant

SECTION I -- PRODUCT IDENTIFICATION

Trade Name and Synonyms:	Silica Gel, Synthetic Amorphous Silica,	
	Silicon, Dioxide	
Chemical Family:	Synthetic Amorphous Silica	
Formula:	SiO ₂ .x H ₂ O	

SECTION II -- HAZARDOUS INGREDIENTS

Components in the Solid Mixture

COMPONENT	CAS No	%	ACGIH/TLV (PPM)	OSHA-(PEL)
Amorphous	63231-67-4	>99	PEL - 20 (RESPIRABLE),	LIMIT – NONE,
Silica			TLV – 5	HAZARD -
				IRRITANT
				"

Synthetic amorphous silica is not to be confused with crystalline silica such as quartz, cristobalite or tridymite or with diatomaceous earth or other naturally occurring forms of amorphous silica that frequently contain crystalline forms.

This product is in granular form and packed in bags for use as a desiccant. Therefore, no exposure to the product is anticipated under normal use of this product. Avoid inhaling desiccant dust.

SECTION III -- PHYSICAL DATA

Appearance and Odor:	White granules; odorless.
Melting Point:	>1600 Deg C; >2900 Deg F
Solubility in Water:	Insoluble.
Bulk Density:	>40 lbs./cu. ft.
Percent Volatile by Weight @ 1750 Deg F:	<10%.





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SECTION IV -- FIRE EXPLOSION DATA

Fire and Explosion Hazard - Negligible fire and explosion hazard when exposed to heat or flame by reaction with incompatible substances.

Flash Point - Nonflammable.

Firefighting Media - Dry chemical, water spray, or foam. For larger fires, use water spray fog or foam.

Firefighting - Nonflammable solids, liquids, or gases: Cool containers that are exposed to flames with water from the side until well after fire is out. For massive fire in enclosed area, use unmanned hose holder or monitor nozzles; if this is impossible, withdraw from area and let fire burn. Withdraw immediately in case of rising sound from venting safety device or any discoloration of the tank due to fire.

SECTION V -- HEALTH HAZARD DATA

Health hazards may arise from inhalation, ingestion, and/or contact with the skin and/or eyes. Ingestion may result in damage to throat and esophagus and/or gastrointestinal disorders. Inhalation may cause burning to the upper respiratory tract and/or temporary or permanent lung damage. Prolonged or repeated contact with the skin, in absence of proper hygiene, may cause dryness, irritation, and/or dermatitis. Contact with eye tissue may result in irritation, burns, or conjunctivitis.

First Aid (Inhalation) - Remove to fresh air immediately. If breathing has stopped, give artificial respiration. Keep affected person warm and at rest. Get medical attention immediately.

First Aid (Ingestion) - If large amounts have been ingested, give emetics to cause vomiting. Stomach siphon may be applied as well. Milk and fatty acids should be avoided. Get medical attention immediately.

First Aid (Eyes) - Wash eyes immediately and carefully for 30 minutes with running water.



NOTE TO PHYSICIAN: This product is a desiccant and generates heat as it adsorbs water. The used product can contain material of hazardous nature. Identify that material and treat accordingly.

SECTION VI -- REACTIVITY DATA

Reactivity - Silica gel is stable under normal temperatures and pressures in sealed containers. Moisture can cause a rise in temperature which may result in a burn.

SECTION VII --SPILL OR LEAK PROCEDURES

Notify safety personnel of spills or leaks. Clean-up personnel need protection against inhalation of dusts or fumes. Eye protection is required. Vacuuming and/or wet methods of cleanup are preferred. Place in appropriate containers for disposal, keeping airborne particulates at a minimum.

SECTION VIII -- SPECIAL PROTECTION INFORMATION

Respiratory Protection - Provide a NIOSH/MSHA jointly approved respirator in the absence of proper environmental control. Contact your safety equipment supplier for proper mask type.

Ventilation - Provide general and/or local exhaust ventilation to keep exposures below the TLV. Ventilation used must be designed to prevent spots of dust accumulation or recycling of dusts.

Protective Clothing - Wear protective clothing, including long sleeves and gloves, to prevent repeated or prolonged skin contact.

Eye Protection - Chemical splash goggles designed in compliance with OSHA regulations are recommended. Consult your safety equipment supplier.





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Packaged Desiccant

SECTION IX -- SPECIAL PRECAUTIONS

Avoid breathing dust and prolonged contact with skin. Silica gel dust causes eye irritation and breathing dust may be harmful.

* No Information Available

HMIS (Hazardous Materials Identification System) for this product is as follows:

Health Hazard	0
Flammability	0
Reactivity	0
Personal Protection	HMIS assigns choice of personal protective equipment to the customer, as the raw material supplier is unfamiliar with the condition of use.

The information contained herein is based upon data considered true and accurate. However, United Desiccants makes no warranties expressed or implied, as to the accuracy or adequacy of the information contained herein or the results to be obtained from the use thereot. This information is offered solely for the user's consideration, investigation and verification. Since the use and conditions of use of this information and the material described herein are not within the control of United Desiccants, United Desiccants assumes no responsibility for injury to the user or third persons. The material described herein is sold only pursuant to United Desiccants' Terms and Conditions of Sale, including those limiting warranties and remedies contained therein. It is the responsibility of the user to determine whether any use of the data and information is in accordance with applicable federal, state or local laws and regulations.

TIENet[®] 360 LaserFlow Ex[®] Velocity Sensor

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